

Thermodynamics

ENGR360-MEP112

LECTURE 3

ENERGY, ENERGY TRANSFER, AND ENERGY ANALYSIS

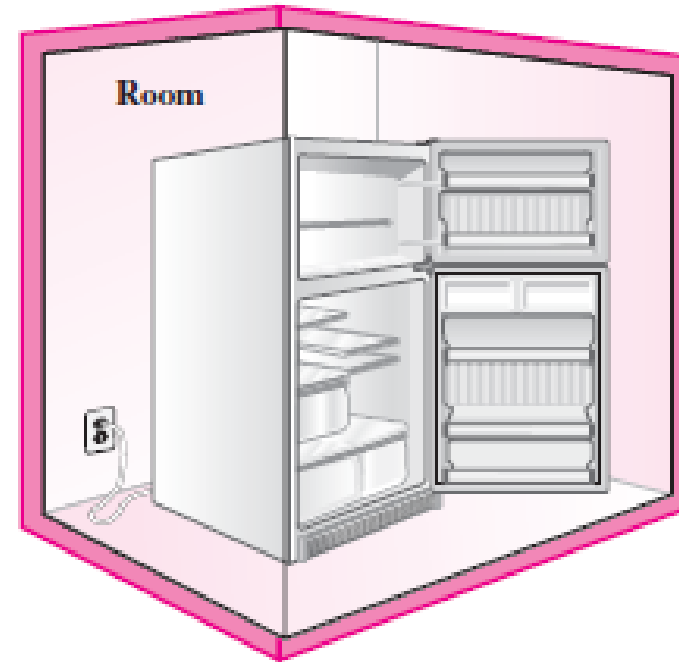
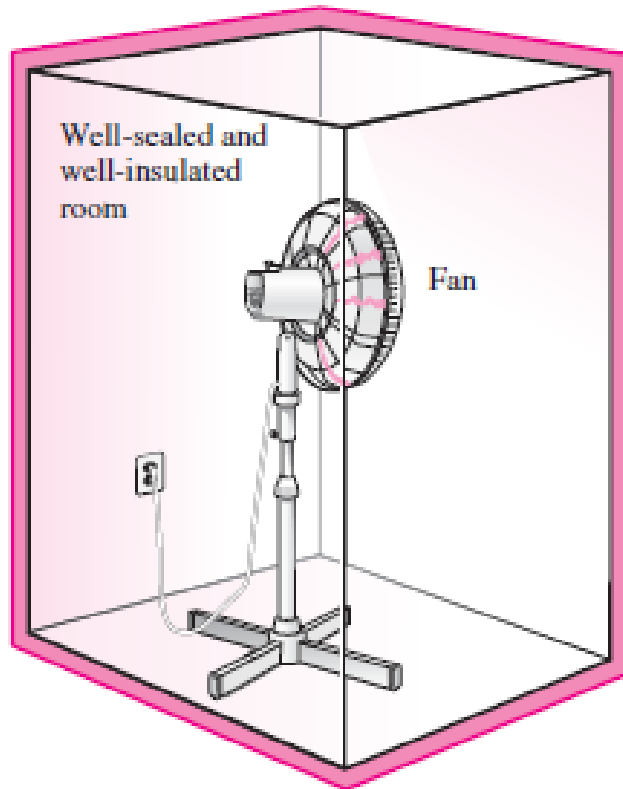
Objectives:

- 1. Introduce the concept of **energy** and define its various **forms**.**
- 2. Discuss the nature of **internal energy**.**
- 3. Define the concept of **heat** and **work** and the terminology associated with each.**

1. CONCEPT OF ENERGY

- ❑ The conservation of energy principle is an expression of the first law of thermodynamics.

Energy cannot be created or destroyed during a process; it can only change from one form to another



A running fan and refrigerator operating with its door open in a well-sealed and well-insulated room.

1. CONCEPT OF ENERGY

□ **Electricity** is of the highest quality of energy. It can always be converted to an equal amount of **thermal energy** (also called **heat**). But only a small fraction of **heat**, which is the lowest quality of energy, can be converted back to **electricity**.

2. FORMS OF ENERGY

□ Energy can exist in numerous forms such as **thermal, mechanical, kinetic, potential, electric, magnetic, chemical, and nuclear**, and their sum constitutes the total energy **E** of a system. The total energy of a system on a unit mass basis is denoted by **e** and is expressed as:

$$e = \frac{E \text{ (Joule)}}{m \text{ (kilogram)}} \text{ (J/kg)}$$

□ Thermodynamics deals with the **change of the total energy (ΔE)**, which is what matters in engineering problems. Thus the total energy of a system can be assigned a value of zero (**$E = 0$**) at some convenient **reference point**. The change in total energy (**ΔE**) of a system is independent of the reference point selected.

2. FORMS OF ENERGY

- ❑ The decrease in the potential energy of a falling rock, for example, depends on only the elevation difference and not the reference level selected.
- ❑ The **macroscopic forms of energy** are those a system possesses as a whole with respect to some outside reference frame such as **kinetic** and **potential** energies.



The macroscopic energy of an object changes with velocity and elevation.

2. FORMS OF ENERGY

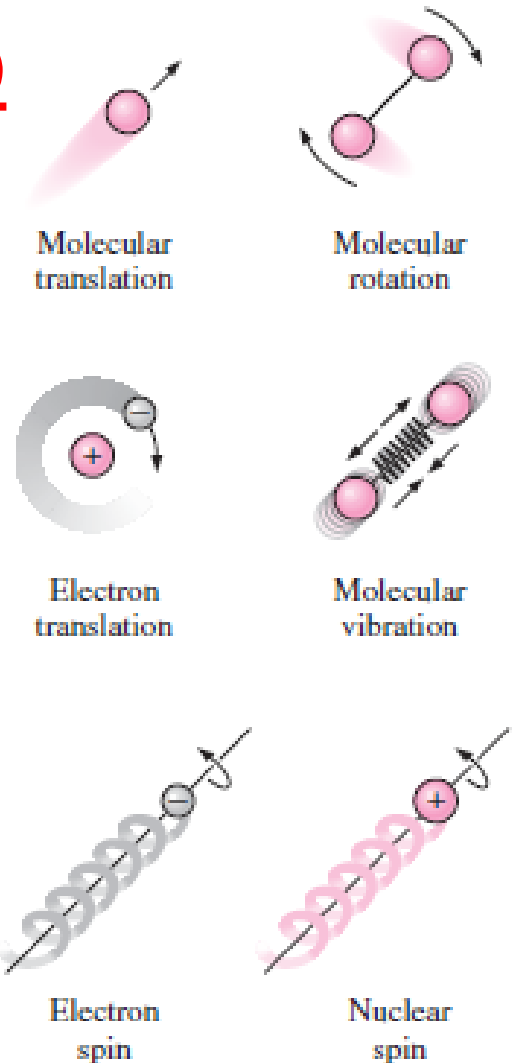
- ❑ The **microscopic forms of energy** are those related to the molecular structure of a system and the degree of the molecular activity, and they are independent of outside reference frames.
- ❑ The **sum** of all the **microscopic forms of energy** is called the **internal energy** of a system and is denoted by **U**.

$$U = \sum \text{Microscopic energy}$$

$$u = \frac{U}{m} \text{ (J/kg)}$$

Physical Insight to Internal Energy (U)

- ❑ **Sensible energy:** is the portion of the internal energy of a system associated with the kinetic energies of the molecules.
- ❑ **Latent energy:** is the portion of the internal energy of a system associated with the phase change of a system.
- ❑ **Chemical energy:** is the portion of the internal energy of a system associated with the atomic bonds in a molecule.



The various forms of microscopic energies that make up *sensible* energy.

2. FORMS OF ENERGY

□ The total energy (**E**) of a system consists of the **kinetic**, **potential**, and **internal energies** and is expressed as:

E = Microscopic part + Macroscopic part

$$\mathbf{E = U + KE + PE = U + m \frac{v^2}{2} + mgz \quad (J)}$$

or, on a unit mass basis

$$\mathbf{e = u + ke + pe = u + \frac{v^2}{2} + gz \quad (J/kg)}$$

Mass flow rate and energy flow rate

- ❑ **Closed systems** whose velocity and elevation of the center of gravity remain constant during a process are frequently referred to as **stationary systems**.
- ❑ **Control volumes** typically involve fluid flow. It is convenient to express the **energy flow** associated with a fluid stream in the **rate form**. This is done by incorporating the mass flow rate (\dot{m}).
- ❑ The **mass flow rate** (\dot{m}): is the amount of mass flowing through a cross section per unit time. It is related to the **volume flow rate** (\dot{V}), which is the volume of a fluid flowing through a cross section per unit time, by:

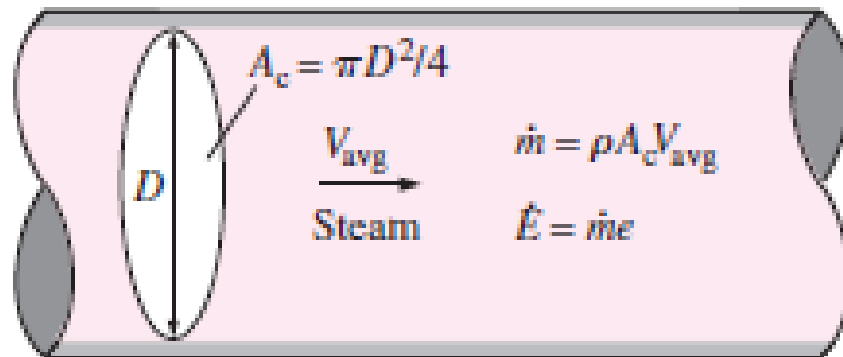
Mass flow rate and energy flow rate

$$\dot{m} = \rho \dot{V} = \rho (\overline{A_c \cdot \vec{v}}) = \rho A_c v_{avg} \text{ (kg/s)}$$

which is analogous to $m = \rho V$. Here ρ is the fluid density, A_c is the cross-sectional area of flow, and V_{avg} is the average flow velocity normal to A_c .

□ Then the energy flow rate \dot{E} associated with a fluid flowing at a rate of \dot{m} is:

$$\dot{E} = \dot{m} e \text{ (Joule/second(J/s) or Watt (W))}$$



Mass and energy flow rates associated with the flow of steam in a pipe of inner diameter D with an average velocity of V_{avg} .

Mechanical Energy

- ❑ **Mechanical energy:** is the form of energy that can be converted completely and directly into mechanical work by an ideal mechanical device such as an *ideal turbine*. Kinetic and potential energies are the familiar forms of mechanical energy.
- ❑ **Thermal energy** is not mechanical energy, however, since it cannot be converted to work directly and completely (the second law of thermodynamics).
- ❑ **Flow work:** is the pressure force acting on a fluid through a distance.

$$e_{\text{mech}} = \frac{p}{\rho} + \frac{v^2}{2} + gz \quad (\text{Energy potential})$$

Mechanical Energy

Or in rate form:

$$\dot{E}_{\text{mech}} = \dot{m} \left(\frac{p}{\rho} + \frac{v^2}{2} + gz \right) \text{ (rate of energy potential)}$$

Then the mechanical energy change of a fluid during **incompressible flow** ($\rho = \text{constant}$) becomes:

$$\Delta e_{\text{mech}} = \left[\frac{p_2 - p_1}{\rho} + \frac{v_2^2 - v_1^2}{2} + g(z_2 - z_1) \right]$$

and in rate form is:

$$\Delta \dot{E}_{\text{mech}} = \dot{m} \left[\frac{p_2 - p_1}{\rho} + \frac{v_2^2 - v_1^2}{2} + g(z_2 - z_1) \right]$$

Mechanical Energy

□ $\Delta \dot{E}_{\text{mech}}$ can be positive, negative or zero!!!

A. $\Delta \dot{E}_{\text{mech}} = 0$:

$$\frac{p_1}{\rho} + \frac{v_1^2}{2} + gz_1 = \frac{p_2}{\rho} + \frac{v_2^2}{2} + gz_2$$

energy

Pressure (flow)

energy

Kinetic

energy

Potential

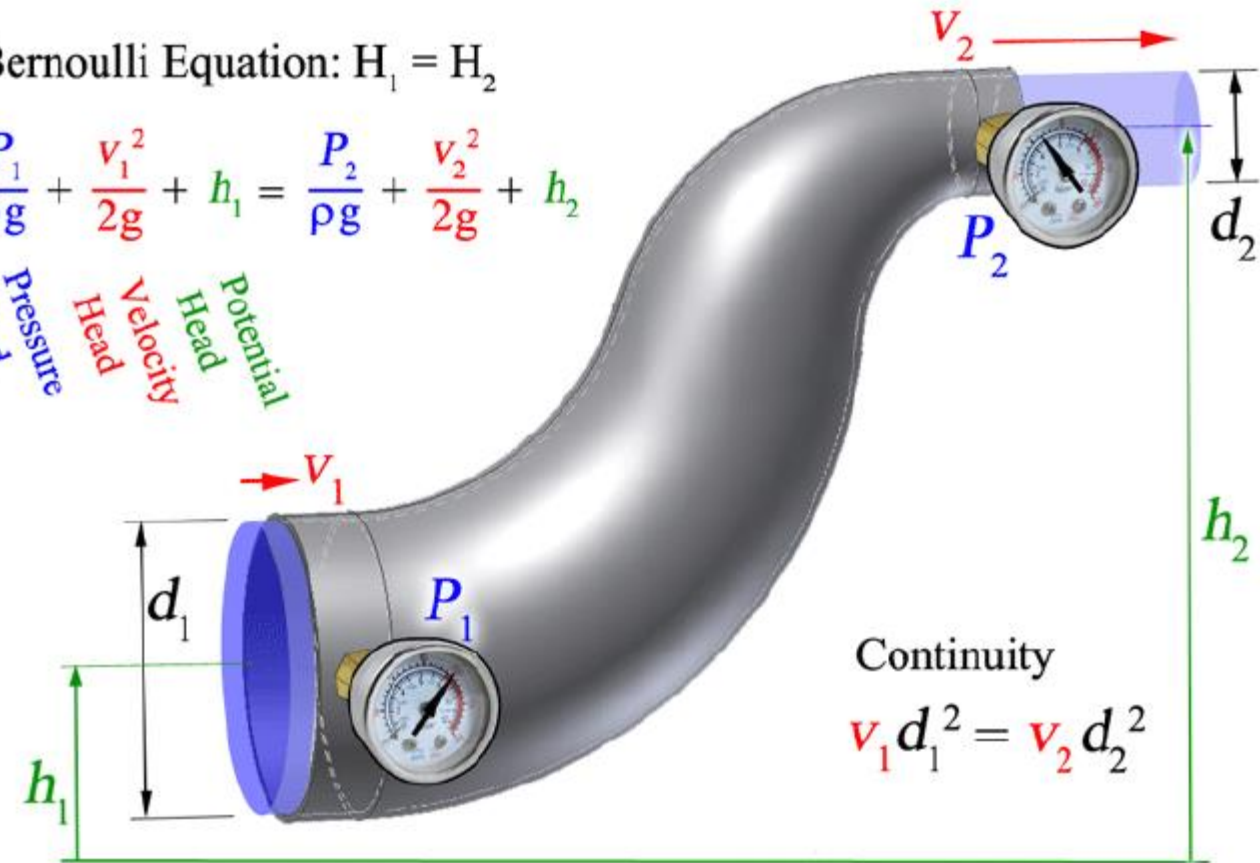
Bernoulli Equation: $H_1 = H_2$

$$\frac{P_1}{\rho g} + \frac{v_1^2}{2g} + h_1 = \frac{P_2}{\rho g} + \frac{v_2^2}{2g} + h_2$$

Pressure Head

Velocity Head

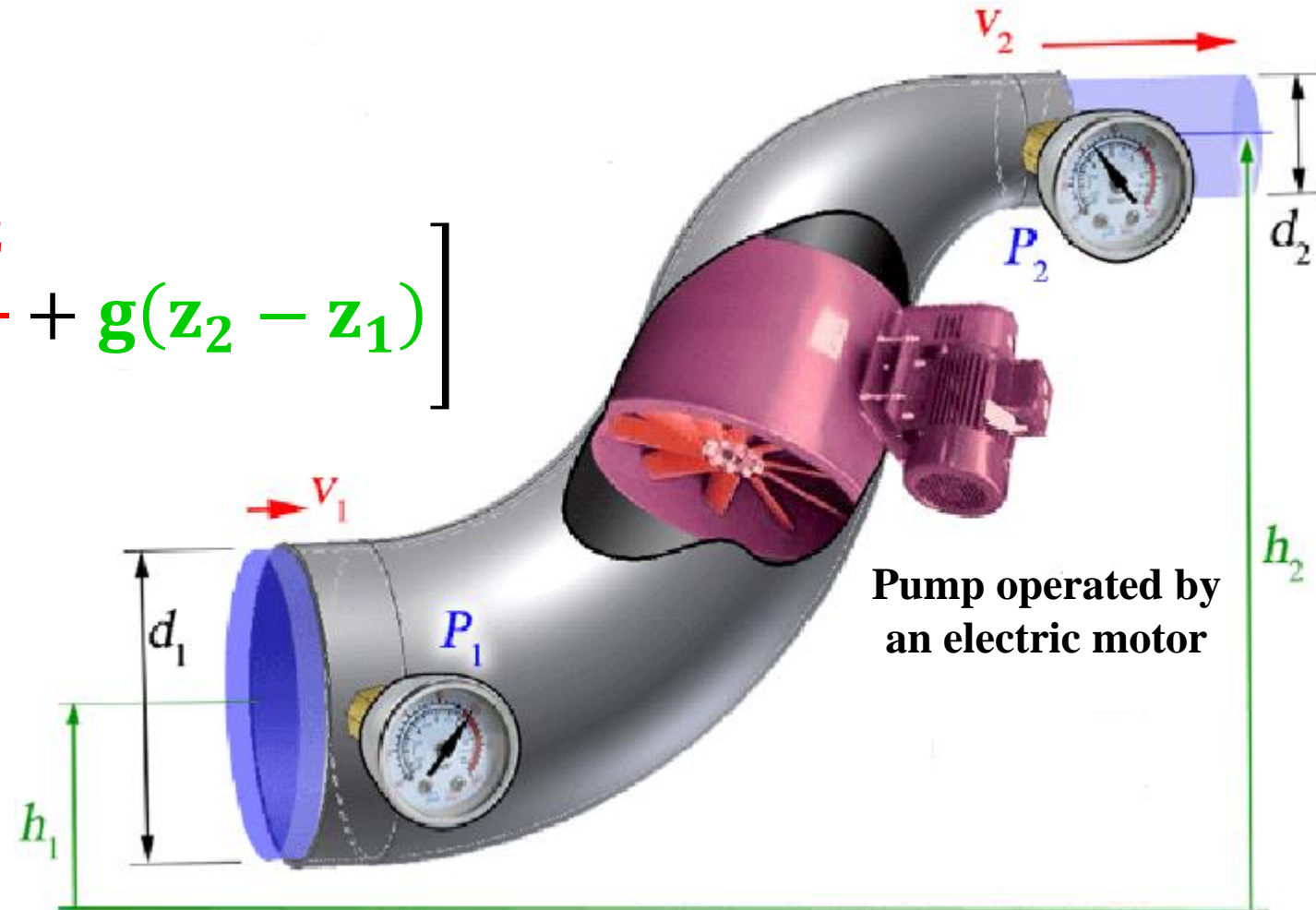
Potential Head



Mechanical Energy

B. $\Delta \dot{E}_{\text{mech}} > 0$:

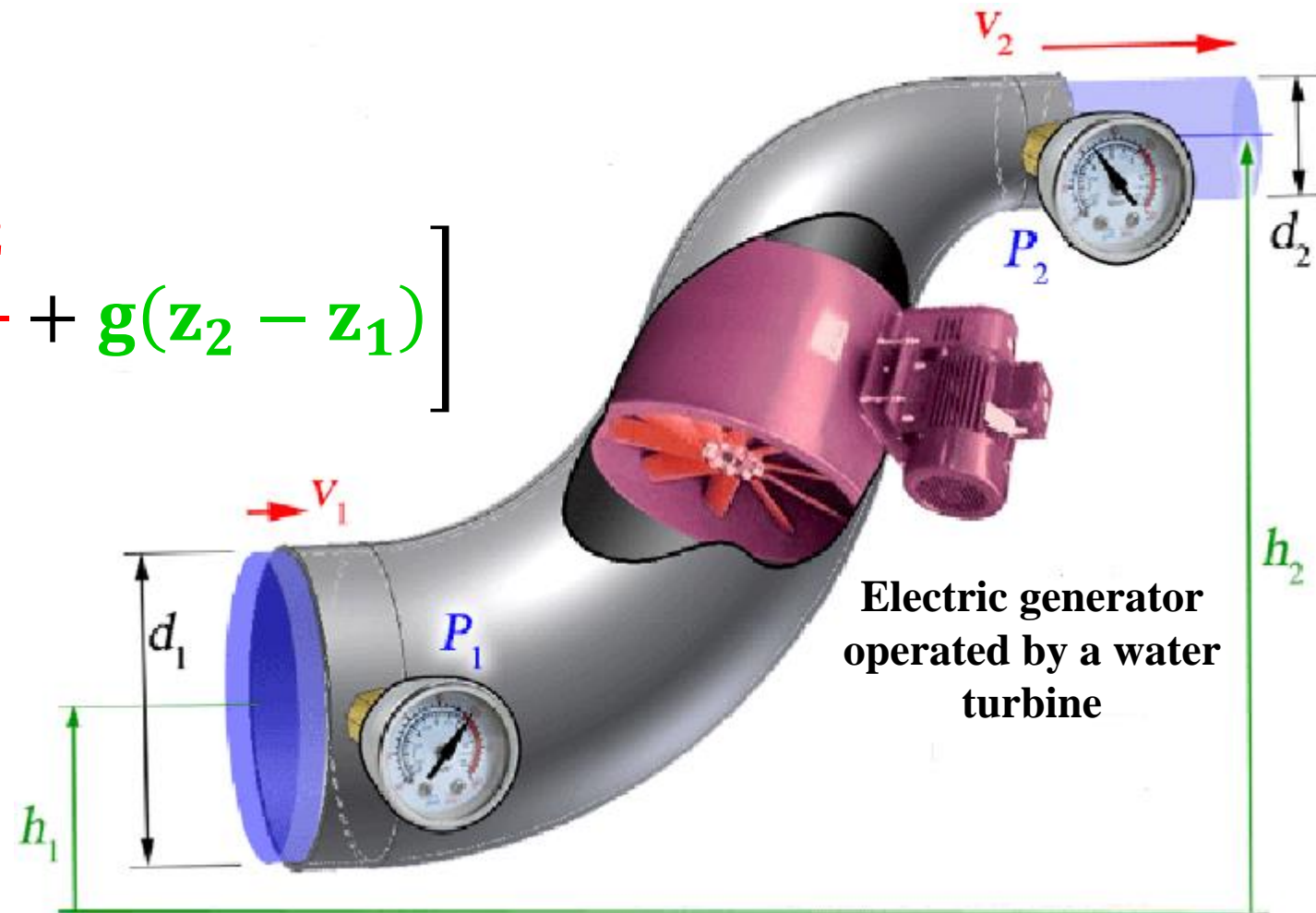
$$\Delta \dot{E}_{\text{mech}} = \dot{m} \left[\frac{p_2 - p_1}{\rho} + \frac{v_2^2 - v_1^2}{2} + g(z_2 - z_1) \right]$$



Mechanical Energy

C. $\Delta \dot{E}_{\text{mech}} < 0$:

$$\Delta \dot{E}_{\text{mech}} = \dot{m} \left[\frac{p_2 - p_1}{\rho} + \frac{v_2^2 - v_1^2}{2} + g(z_2 - z_1) \right]$$



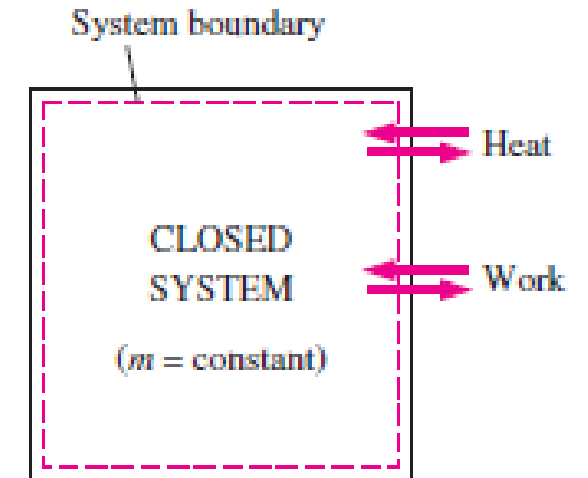
3. ENERGY TRANSFER BY WORK



3. ENERGY TRANSFER BY WORK

- ❑ Energy can cross the boundary of a closed system in two distinct forms: **work** and **heat**.
- ❑ **Work**: is an energy interaction that is not caused by temperature difference between a system and its surroundings.
- ❑ The work done per unit time is called **power** (\dot{W}) and its unit is **Watt (W)**.
- ❑ The work done per unit mass of a system is denoted by **w** and is expressed as:

$$w = \frac{W}{m} \text{ (J/kg)}$$

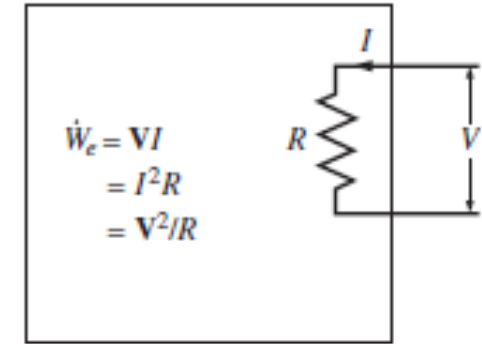


Energy can cross the boundaries of a closed system in the form of heat and work.

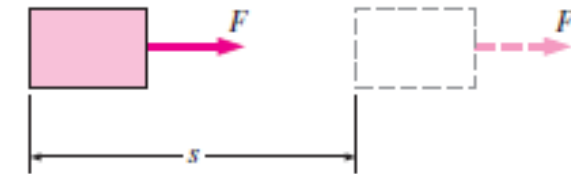
3. ENERGY TRANSFER BY WORK

A. Electrical Work:

$$W_e = \int_1^2 VI dt$$



Electrical power in terms of resistance R , current I , and potential difference V .



The work done is proportional to the force applied (F) and the distance traveled (s).

B. Displacement Work:

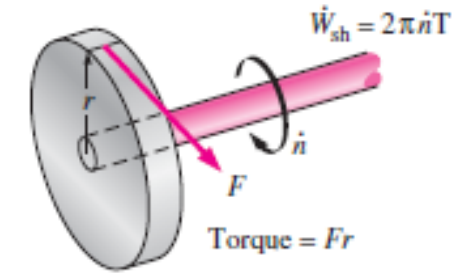
$$W_d = \int_1^2 F ds$$

3. ENERGY TRANSFER BY WORK

C. Shaft Work:

$$W_{sh} = \text{Force} \times \text{distance} = \left(\frac{T}{r}\right) \cdot 2\pi r n = 2\pi n T$$

$$\dot{W}_{sh} = 2\pi \dot{n} T$$



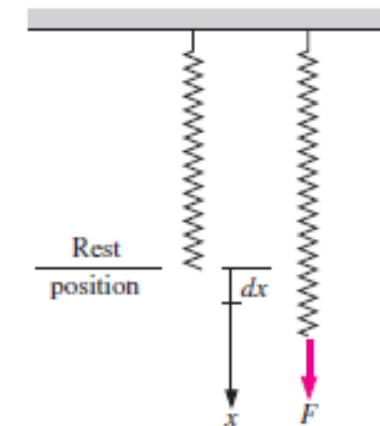
Shaft work is proportional to the torque applied and the number of revolutions of the shaft.

D. Spring Work:

$$F_{sp} = Kx, \quad \text{where } K \text{ is the spring constant}$$

$$W_{sp} = \int_1^2 F_{sp} dx = \int_1^2 Kx dx$$

$$W_{sp} = \frac{1}{2} K(x_2^2 - x_1^2)$$



Elongation of a spring under the influence of a force.

4. ENERGY TRANSFER BY HEAT

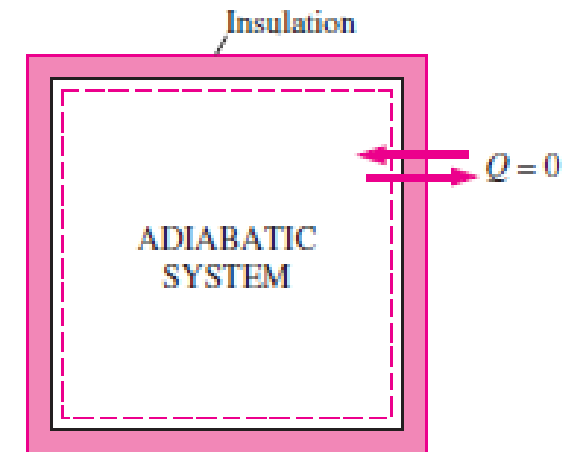
- ❑ **Heat:** is the form of energy that is transferred between a system and its surroundings by the potential of temperature difference.
- ❑ A process during which there is no heat transfer is called an **adiabatic process**.

Insulated system \equiv **Adiabatic system**

Adiabatic process \equiv **No heat transfer ($Q=0$)**

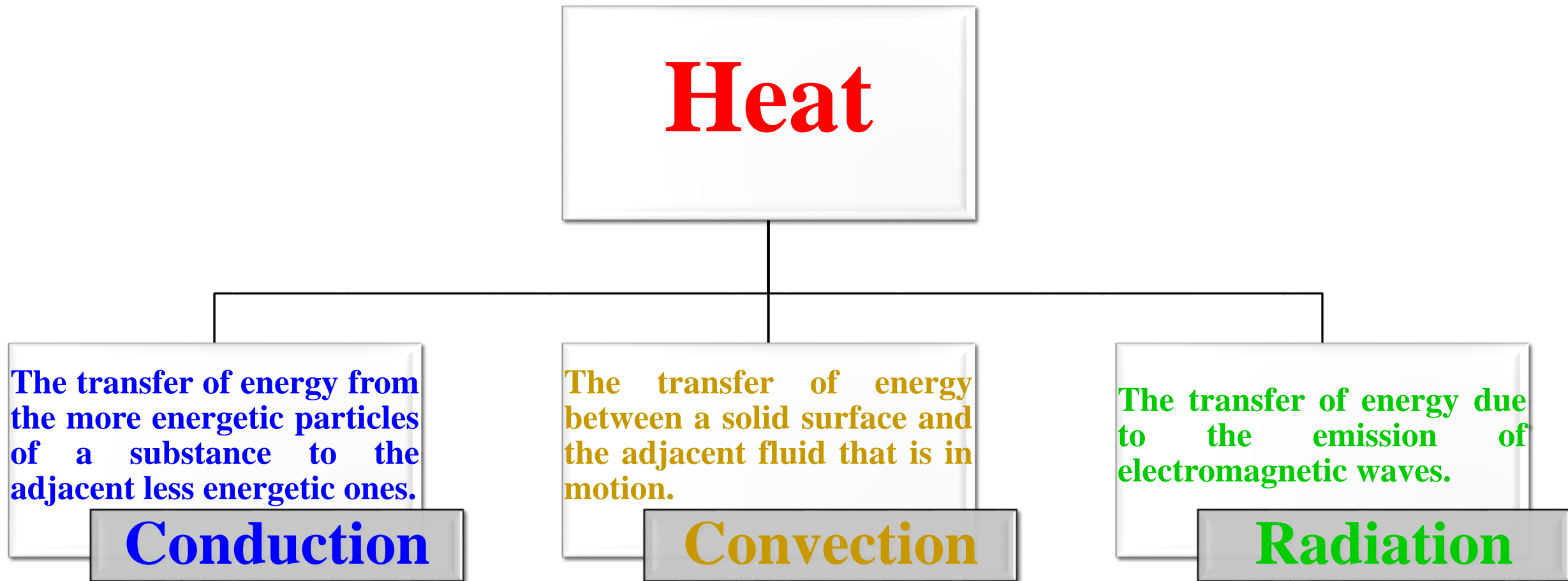
- ❑ Heat transfer per unit mass of a system is denoted **q** and is expressed as:

$$q = \frac{Q}{m} \text{ (J/kg)}$$



- ❑ **Heat transfer rate (\dot{Q}):** is the heat transfer per unit time.

4. ENERGY TRANSFER BY HEAT



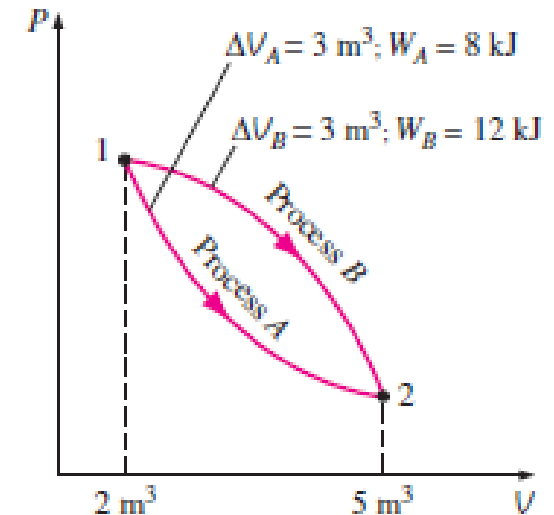
Point and path functions

- **Properties** are **point functions**. They depend on the state only, and not on how a system reaches that state.
- **Heat** and **work** are **path function**. Each is not a property and systems do not possess **work** or **heat** at a state.

$$W = \int_1^2 \delta W \neq \boxed{W_2 - W_1}$$

$$Q = \int_1^2 \delta q \neq \boxed{q_2 - q_1}$$

Meaningless !!!



Properties are point functions; but heat and work are path functions (their magnitudes depend on the path followed).